# Finite Time Extinction in Nonlinear Diffusion Equations 

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#### Abstract

We consider a class of degenerate diffusion equations where the nonlinearity is assumed to be singular (non-Lipschitz) at zero. It is shown that solutions with compactly supported initial data become identically zero in finite time. Such extinction follows by comparison with newly constructed finite travelling waves connecting two stable equilibria. © 2004 Elsevier Ltd. All rights reserved.


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## 1. INTRODUCTION

This paper is concerned with the quasilinear parabolic equation

$$
\begin{gather*}
u_{t}=d\left(u^{m+1}\right)_{x x}+f(u), \quad(x, t) \in Q:=\mathbb{R} \times(0, \infty),  \tag{1}\\
u(x, 0)=u_{0}(x), \quad x \in \mathbb{R}, \quad 0 \leq u_{0} \leq 1, \tag{2}
\end{gather*}
$$

where $m>0, d=1 /(m+1), u_{0} \in C(\mathbb{R})$, and $f$ satisfies the following.
(A1) $f \in C[0,1] \cap C^{1}(0,1], f(0)=f(1)=0$, and $f^{\prime}(1)<0$. Moreover, $\exists \alpha \in(0,1)$ such that $f<0$ on $(0, \alpha)$ and $f>0$ on $(\alpha, 1)$.
(A2) $\exists p \in(0,1)$ and $\beta>0$ such that $N:=m+p \geq 1$ and $u^{-p} f(u) \rightarrow-\beta$ as $u \rightarrow 0^{+}$.
(A3) $\int_{0}^{1} v^{m} f(v) d v<0$.

Assumptions (A1)-(A3) will collectively be referred to as (A). Such diffusion equations arise in many applications, including population genetics, signal propagation in nerve axons, and combustion theory $[1-4]$.
In this paper, we establish the existence of a unique (modulo translation) finite travelling wave (FTW) $v_{\omega}(z)$ of (1) satisfying $v_{\omega}(-\infty)=1$ and $v_{\omega}(z)=0$ for all $z \geq \omega$, for any $\omega \in \mathbb{R}$ (see Section 3). In particular, $v_{\omega}$ has negative velocity. By an FTW, we mean any travelling wave (TW) solution $u(x-c t)$ of (1) satisfying $u(z)=0$ for all $z \geq \omega$ (or $z \leq \omega$ ) for some $\omega \in \mathbb{R}$. Utilising $v_{\omega}$ and its reflection as upper solutions, we then deduce the finite time extinction of compactly supported solutions of (1),(2). This follows from an existence-uniqueness-comparison result in Section 2. Finally, we apply our results to a singular bistable nonlinearity and present some numerical simulations.
In the case of a smooth bistable nonlinearity $f \in C^{2}[0, \infty)$, Hosono [5] proved the existence and stability of a unique FTW with nonnegative velocity satisfying $u(-\infty)=1$ and $u(z)=0$ for all $z \geq 0$, provided $\int_{0}^{1} u^{m} f(u) d u \geq 0$. However, when the reverse integral inequality holds in [5] there are no FTW solutions connecting the equilibria. It is precisely the regularity of $f$ at the degenerate point $u=0$ which excludes the existence of such waves in the nonsingular case.

We remark that while finite time extinction phenomena are known to exist in absorptive heat equations of the form

$$
\begin{equation*}
u_{t}=d\left(u^{m+1}\right)_{x x}-C u^{p}, \quad 0<p<1 \tag{3}
\end{equation*}
$$

(see [6] and the references therein), we are unaware of any results in this direction for signchanging nonlinearities. In particular, for initial data satisfying $f\left(u_{0}(x)\right)>0$ for some $x$, one cannot deduce the finite time extinction property in the general case via comparison with solutions of (3).

## 2. PRELIMINARIES

Before proceeding to the study of TW solutions, we first settle the question of existence, uniqueness, and comparison of solutions for the Cauchy problem (1),(2). Here and throughout, $Q_{T}:=\mathbb{R} \times(0, T)$.

Definition 2.1. A nonnegative function $u$ is said to be a weak solution of (1),(2) if and only if for every $r, T>0, u \in C\left(Q_{T}\right) \cap L^{\infty}\left(Q_{T}\right)$ and

$$
\begin{aligned}
\int_{Q_{T}} u \phi_{t}+d u^{m+1} \phi_{x x}+f(u) \phi d x d t= & \int_{-r}^{r} u(x, T) \phi(x, T)-u_{0}(x) \phi(x, 0) d x \\
& +d \int_{0}^{T} u^{m+1}(r, t) \phi_{x}(r, t)-u^{m+1}(-r, t) \phi_{x}(-r, t) d t
\end{aligned}
$$

for all $\phi \in C^{2,1}\left(\bar{Q}_{T}\right)$ such that $\phi \geq 0$ and $\phi( \pm r, t)=0$ for all $t \in[0, T]$.
Lemma 2.1. If (A1),(A2) hold then there exists a unique weak solution $u$ of (1),(2). Moreover, if $u$ and $v$ denote the solutions of (1),(2) with initial data satisfying $0 \leq u_{0} \leq v_{0} \leq 1$ in $\mathbb{R}$, then $0 \leq u \leq v \leq 1$ in $Q$.
Proof. The proof is identical to [7, Theorems 2.5 and 2.10 ] except for a minor modification to allow for the sign-changing nonlinearity $f$ considered here. The vital ingredient which allows us to generalise the result in $[7]$ is the upper Lipschitz condition

$$
\begin{equation*}
\exists K>0 \text { such that } f(v)-f(u) \leq K(v-u), \quad \text { for all } 0 \leq u \leq v \leq 1, \tag{4}
\end{equation*}
$$

which holds due to (A1),(A2). Below, we outline the modification required.

Existence follows via the following well-known construction. For $k \in \mathbb{N}$ denote by $\left(P_{k}\right)$ the problem

$$
\begin{gathered}
u_{t}=d\left(u^{m+1}\right)_{x x}+f(u)-f\left(\epsilon_{k}\right), \quad(x, t) \in Q_{k, T}:=(-k, k) \times(0, T), \\
u( \pm k, t)=M:=\sup _{x \in(-\infty, \infty)} u_{0}(x), \quad t \in[0, T], \\
u(x, 0)=\psi_{0, k}(x), \quad x \in[-k, k] .
\end{gathered}
$$

Here, $\epsilon_{k} \rightarrow 0$ as $k \rightarrow \infty$ and $\psi_{0, k}$ is a monotone decreasing sequence converging to $u_{0}$ (see [7, Section 4.A]). By classical results for uniformly parabolic equations, the solution sequence $u_{k}$ is monotone decreasing and bounded below by $\epsilon_{k}>0$. The pointwise limit function $u \in L^{\infty}\left(Q_{T}\right)$ then satisfies the integral identity in Definition 2.1.

To obtain uniqueness, suppose that $\hat{u}$ is any other solution of (1),(2). By comparison for $\left(P_{k}\right)$, $\hat{u} \leq u_{k}$ for all $k$ so that $\hat{u} \leq u$. Hence, it is sufficient to prove that for any fixed $t \in(0, T]$, $\chi \in C_{0}^{\infty}(\mathbb{R}), 0 \leq \chi \leq 1$ and $\epsilon>0$, there exists an $r>0$ such that

$$
\int_{-r}^{r}(u(x, t)-\hat{u}(x, t)) \chi(x) d x<\epsilon
$$

(see [7, equation (4.3)]). We define $a_{k}$ as in [7, Section 3.B] by

$$
a_{k}(x, t)= \begin{cases}\frac{d\left(\hat{u}^{m+1}-u_{k}^{m+1}\right)}{\left(\hat{u}-u_{k}\right)}, & u_{k} \neq \hat{u}, \\ \hat{u}^{m}, & u_{k}=\hat{u}\end{cases}
$$

and note that since $u_{k} \geq \epsilon_{k}$, the bound $a_{k} \geq C(k):=\epsilon_{k}^{m}$ holds as in [7, equation (3.10)]. The only modification we need to make is in the choice of $b_{k}$ in [7, Section 4.B]. Due to the lack of monotonicity of $f$ in our case, we take

$$
b_{k}(x, t)= \begin{cases}\frac{\left(f\left(u_{k}\right)-f(\hat{u})\right)}{\left(\hat{u}-u_{k}\right)}+K, & u_{k} \neq \hat{u}, \\ K-f^{\prime}(\hat{u}), & u_{k}=\hat{u} .\end{cases}
$$

By (4), it follows that $0 \leq b_{k} \leq C_{3}(k)$ as in [7, equation (4.5)]. The integral identity [7, equation (4.6)] then has the extra term $\iint K\left(u_{k}-\hat{u}\right) \phi_{k, n}$ on the right-hand side. Letting $n \rightarrow \infty$, then $k \rightarrow \infty$ and noting that $\phi_{k, n} \leq 1$, one then has the inequality

$$
\int_{-r}^{r}(u(x, t)-\hat{u}(x, t)) \chi(x) d x<\epsilon+K \int_{0}^{t} \int_{-r}^{r}(u(x, s)-\hat{u}(x, s)) d x d s
$$

for $r$ sufficiently large. Hence, by Gronwall's lemma

$$
\int_{-r}^{r}(u(x, t)-\hat{u}(x, t)) \chi(x) d x<\epsilon e^{K t} .
$$

Since $t$ is fixed and $\epsilon$ is arbitrary, this gives the required result.
Comparison and continuity of $u$ follow from [7, Theorems 2.10 and 2.5].

## 3. FINITE TRAVELLING WAVES AND EXTINCTION

Let us write (1) in the divergence form

$$
u_{t}=\left(u^{m} u_{x}\right)_{x}+f(u), \quad(x, t) \in Q .
$$

Setting $z=x-c t, u$ is (formally) a TW solution of (1), with velocity $c$, if and only if $u$ satisfies the quasilinear ordinary differential equation (ODE)

$$
\begin{equation*}
-c u^{\prime}=\left(u^{m} u^{\prime}\right)^{\prime}+f(u), \quad z \in \mathbb{R} \tag{5}
\end{equation*}
$$

where ${ }^{\prime}=\frac{d}{d z}$. Following $[8,9]$, if we rescale the 'time' variable $z$ according to

$$
\begin{equation*}
\frac{d s}{d z}=\frac{1}{u^{m}(z)} \tag{6}
\end{equation*}
$$

and set $U(s)=u(z)$, then $u(z)$ is a (weak) TW solution of (1) if and only if $U(s)$ is a (classical) TW solution of

$$
\begin{equation*}
U_{t}=U_{x x}+U^{m} f(U), \quad(x, t) \in Q \tag{7}
\end{equation*}
$$

or equivalently,

$$
\begin{equation*}
-c \dot{U}=\ddot{U}+U^{m} f(U), \quad s \in \mathbb{R} \tag{8}
\end{equation*}
$$

where $=\frac{d}{d s}$. We call (8) the desingularised $O D E$ since by (A1), (A2), $U^{m} f(U) \in C^{1}[0,1]$.
Initially, we seek TW solutions of (7) for $c>0$ connecting the equilibria $U=0$ and $U=1$. The following result can be found in [2, Theorem $2.4(\mathrm{~b})$ and equation (2.7)].
Lemma 3.1. If ( $A$ ) holds, then there exists a unique wave speed $c^{*}>0$ such that (8) has a positive solution $U^{*}(s)$ satisfying $U^{*}(-\infty)=0$ and $U^{*}(\infty)=1$. Moreover, $U^{*}$ is monotone in $s$.

Now let $c>0$ and write (8) as the first-order system

$$
\begin{align*}
\dot{U} & =V  \tag{9}\\
\dot{V} & =-c V-U^{m} f(U) \tag{10}
\end{align*}
$$

System (9),(10) possesses equilibria at $(0,0)$ and $(1,0)$. Linearisation about these points then yields the local flow. (Of course, technically one would need to extend the functions $U^{m}$ and $f(U)$ smoothly to include $U \leq 0$ in order to define a smooth vector field in an open neighbourhood of the origin, but the flow in the right-half plane would remain unaltered.) The equilibrium ( 1,0 ) is a hyperbolic saddle point. The topological type of $(0,0)$ depends on the value of $N$ as follows.

If $N>1$, the origin is nonhyperbolic and has a one-dimensional stable manifold $W^{s}(0,0)$ tangent to the eigenvector $(1,-c)^{T}$ with corresponding eigenvalue $\lambda=-c$, and a one-dimensional centre manifold $W^{c}(0,0)$ tangent to the eigenvector $(1,0)^{T}$ with corresponding eigenvalue $\lambda=0$. (Note that the superscript in $W^{c}(0,0)$ signifies the centre manifold and not its dependence on the wave speed c.) A straightforward centre manifold reduction [10, Theorem 3, p. 25] gives the local representation of $W^{c}(0,0)$, restricted to $U \geq 0$, as a graph over $U$ given by

$$
\begin{equation*}
V=\frac{\beta}{c} U^{N}+o\left(U^{N}\right), \quad \text { as } U \rightarrow 0^{+} \tag{11}
\end{equation*}
$$

Consequently, the local flow of (9),(10) restricted to $W^{c}(0,0)$ for $U \geq 0$, is unstable.
If $N=1$, the origin is a hyperbolic saddle with corresponding eigenvalues

$$
\begin{equation*}
\lambda_{ \pm}(c):=\frac{1}{2}\left(-c \pm \sqrt{c^{2}+4 \beta}\right) \tag{12}
\end{equation*}
$$

and stable and unstable manifolds $W^{s}(0,0)$ and $W^{u}(0,0)$ tangent to the eigenvectors $\left(1, \lambda_{-}\right)^{T}$ and $\left(1, \lambda_{+}\right)^{T}$, respectively.

Candidates for FTWs of (1) are rescaled solutions of (9), (10) satisfying $(U(s), V(s)) \rightarrow(0,0)$ as $s \rightarrow-\infty$ along $W^{c}(0,0)$ when $N>1$, or $W^{u}(0,0)$ when $N=1$. We now show that the departure times along these invariant manifolds are finite in the original $z$ time scale while establishing
sufficient regularity required of a weak solution. In what follows, we define the departure time $\omega \in[-\infty, \infty]$ by $u(\omega)=0$.

For $N=m+p=1, W^{u}(0,0)$ has the local form $V=\lambda_{+} U+o(U)$, by Hartman-Grobman. Hence,

$$
\begin{equation*}
\frac{d u}{d z}=\frac{d U}{d s} \frac{d s}{d z}=\frac{\lambda_{+} u+o(u)}{u^{m}}, \quad \text { as } u \rightarrow 0^{+} \tag{13}
\end{equation*}
$$

by (6) and (9). Integrating (13) from $z=\omega$ to $z$, one obtains $m \lambda_{+}(z-\omega)=u^{m}+o\left(u^{m}\right)$. Hence, $\omega$ is finite and we have the regularity result

$$
\begin{equation*}
u=O\left((z-\omega)^{1 /(1-p)}\right), \quad \text { as } z \rightarrow \omega^{+} \tag{14}
\end{equation*}
$$

When $N>1$ and we consider solutions departing along $W^{c}(0,0)$, the local form (11) together with (6) yield

$$
\frac{d u}{d z}=\frac{d U}{d s} \frac{d s}{d z}=\frac{(\beta / c) u^{N}+o\left(u^{N}\right)}{u^{m}}=\frac{\beta}{c} u^{p}+o\left(u^{p}\right)
$$

Integrating from $z=\omega$ to $z$, one obtains $\beta(z-\omega)=c u^{1-p} /(1-p)+o\left(u^{1-p}\right)$ and again $\omega$ is finite. Consequently, we have the regularity result $u(z)=O\left((z-\omega)^{1 /(1-p)}\right)$ as $z \rightarrow \omega^{+}$, just as in (14).

Using the finite time departure in $z$ along $W^{u}(0,0)(N=1)$ or $W^{c}(0,0)(N>1)$, we may construct the FTWs of (1) connecting $u=0$ and $u=1$. By Lemma 3.1, there exists a unique TW (modulo translation) $U^{*}(s)$ of (7) for $c=c^{*}>0$ satisfying $U^{*}(s) \rightarrow 0$ as $s \rightarrow-\infty$ and $U^{*}(s) \rightarrow 1$ as $s \rightarrow \infty$. Clearly, this solution corresponds to a trajectory $\left(U^{*}, V^{*}\right)$ of $(9),(10)$ leaving ( 0,0 ) along $W^{u}(0,0)(N=1)$ or $W^{c}(0,0)(N>1)$ at $s=-\infty$ and arriving at $(1,0)$ at $s=\infty$. For any $\omega \in \mathbb{R}$, the rescaling (6) now gives rise to a function $u^{*}(z)$, defined for all $z \geq \omega$, satisfying $u^{*}(z) \rightarrow 0$ as $z \rightarrow \omega^{+}$and $u^{*}(z) \rightarrow 1$ as $z \rightarrow \infty$. Furthermore, the regularity estimate (14) holds for $u^{*}$. Defining the extended function $u_{\omega}(z)$ by

$$
u_{\omega}(z)= \begin{cases}0, & z \leq \omega \\ u^{*}(z), & z>\omega\end{cases}
$$

it then follows that $u_{\omega}(z)$ is a weak FTW solution of (1). Hence, we have the following.
Theorem 3.1. Assume (A) holds and let $\omega \in \mathbb{R}$. There exists a unique $c^{*}>0$ such that ( 1 ) has a finite travelling wave solution $u_{\omega}(z)$ satisfying $u_{\omega}(z)=0$ for all $z \leq \omega$ and $u_{\omega}(\infty)=1$. Furthermore, $u_{\omega}(z)$ is monotone in $z$ and the regularity estimate (14) holds.

Note that by setting $v_{\omega}(z)=u_{\omega}(-z)$, we obtain the negative velocity FTW referred to in the Introduction. Our finite time extinction result for (1),(2) now easily follows.
Corollary 3.1. If (A) holds and $u_{0}$ has compact support, then the solution $u$ of (1), (2) has compact support for all $t>0$ and there exists a $T \geq 0$ such that $u(x, t) \equiv 0$ for all $t \geq T$.
Proof. First, observe that $u$ is a subsolution of the linear porous medium equation $v_{t}=$ $d\left(v^{m+1}\right)_{x x}+C v$ with the same initial data (for sufficiently large $C>0$ ) and so by standard theory $u$ has compact support for all $t \geq 0$. Second, since $u_{0} \not \equiv 1$ and the solution $u$ is classical away from $u=0$, it follows that $u<1$ in $Q$. Hence, for any $\epsilon>0$, we may bound $u(x, \epsilon)$ above by suitable translates $u_{\omega_{1}}(z)$ and $v_{\omega_{2}}(z)$. Extinction then follows by comparison for all $t \geq \epsilon$ and the fact that $\min \left\{u_{\omega_{1}}, v_{\omega_{2}}\right\} \equiv 0$ after some finite time $T$.
Remark 3.1. Clearly, Corollary 3.1 holds for more general $f$ provided there exists a solution of (8) satisfying $U^{*}(-\infty)=0$ and $U^{*}(\infty)=1$ for some $c^{*}>0$. If $f$ has more than one zero in $(0,1)$, then (A3) is a necessary, but not a sufficient condition for the existence of such a TW. For such cases, sufficient conditions are given in [2, Theorem 2.7]. For example, suppose $f$ has three simple zeros $0<\alpha_{1}<\alpha_{2}<\alpha_{3}<1$ such that $P\left(\alpha_{1}\right)<P\left(\alpha_{2}\right)<P(1)<0$ and $P\left(\alpha_{3}\right)<P\left(\alpha_{2}\right)$, where $P(u):=\int_{0}^{u} v^{m} f(v) d v$. Three applications of [2, Theorem 2.7] over $\left[0, \alpha_{2}\right],\left[\alpha_{2}, 1\right]$, and $[0,1]$ then yields the required TW and Corollary 3.1 applies.

## 4. AN EXAMPLE: NAGUMO'S EQUATION

Consider the special case where $f(u)=u^{p}(u-\alpha)(1-u)$, where $0<\alpha, p<1$. For $p=1$, (1) is commonly known as Nagumo's equation, used in modelling electrical pulse propagation in nerve axons and in population genetics to model the allele effect [1,4]. As far as we are aware, all existing literature on Nagumo's equation assumes that $p \geq 1$. The singularity assumption $p<1$ appears to be new.

A simple calculation shows that (A) holds if and only if $\alpha>\alpha^{*}:=(N+1) /(N+3)$. Figure 1a shows the finite time extinction of solutions proved in Corollary 3.1 when $\alpha>\alpha^{*}$. Figure 1b depicts convergence to the FTW $u_{\omega}$ of Theorem 3.1 and its reflection $v_{\omega}$. Note the formation of a region $\Omega_{0}$ in $Q$ where the solution is identically zero even though the initial data is everywhere positive. Such a region is commonly known as a dead core [11].
In the special case $N=1$, one can in fact verify that the FTW $u_{\omega}$ of Theorem 3.1 is given by the solution of the ODE

$$
\begin{equation*}
\frac{d u}{d z}=\frac{1}{\sqrt{2}} u^{p}(1-u), \quad u(\omega)=0, \quad u(\infty)=1 \tag{15}
\end{equation*}
$$

Furthermore, when $m=p=1 / 2$, (15) admits the explicit solution

$$
u=\left(\left[\tanh \left(\frac{z-\omega}{2 \sqrt{2}}\right)\right]^{+}\right)^{2}
$$



Figure 1. Numerical solutions of (1) for $f(u)=u^{p}(u-a)(1-u)$ with $m=3, p=0.5$, and $a=0.85>a^{*}=9 / 13$. The top figure illustrates finite time extinction while the bottom figure shows the emergence of a dead core.

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